

# A CLASS OF PIECEWISE LINEAR MAPS

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ABSTRACT. Piecewise linear functions defined by p-maps, linear only on a subset of  $r$  vectors and components, are introduced. Universal properties for this maps are proved. Spaces of extensions of differential forms by piecewise linear functions are considered.

## 1. INTRODUCTION

Piecewise linear functions are useful in several different contexts, piecewise linear manifolds, computer science or convex analysis are examples. A definition of a piecewise linear function is the following, see [8]. Let  $C$  a closed convex domain in  $\mathfrak{R}^d$ , a function  $\Phi : C \rightarrow \mathfrak{R}$  is said to be piecewise linear if there is a finite family  $\mathcal{Q}$  of closed domains such that  $C = \cup \mathcal{Q}$  and  $\Phi$  is linear on every domain in  $\mathcal{Q}$ . A linear function  $\phi$  on  $\mathfrak{R}^d$  which coincides with  $\Phi$  on some  $Q_i \in \mathcal{Q}$  is said to be a component of  $\Phi$ . In this paper is considered a more general class of piecewise linear functions. It is defined the set of maps  $SW(E^m, T)$  which are linear only on a subset of  $r$  vectors and components. Then an exponential functor  $F$  is defined from linear spaces to the set  $SW(E^m, T)$ . It is proved the uniqueness and existence of a function  $\otimes$  as universal element for the functor  $F$ . It is defined a  $r$ -subsetwise linear skewsymmetric  $\Phi = \sum_{\mu, \nu} \lambda_{\nu}^{\mu} \phi$  map and it is proved that this is completely determined by its values for  $\lambda_{\nu}^{\mu}$  and on a basis of  $E$ . A  $r$ -determinant function is defined as a  $r$ -subsetwise linear skewsymmetric map  $\Phi : E^m \rightarrow \Gamma$ , where  $\Gamma$  is an arbitrary field of characteristic 0. Some properties of  $r$ -determinant maps are considered. It is defined the adjoint for a linear map  $\psi \in L(E, F)$ , where  $E$  and  $F$  are linear spaces, and the development of a  $r$ -determinant function by  $r$ -cofactors. Extensions of differential forms are defined by  $r$ -subsetwise skewsymmetric maps. Basis and spaces of generalized differential forms are studied.

## 2. R-SUBSETWISE LINEAR MAPPINGS

Some properties of linear functions are extended to mappings which are linear only on subsets of  $r$  variables.  $\Gamma$  denotes an arbitrarily chosen field such that  $char \Gamma = 0$ . The multindex  $I_r^n$  of length  $r$  is defined by

$$I_r^n = \{(i_1, \dots, i_r) : 1 \leq i_1 < i_2 < \dots < i_r \leq n\}$$

besides, for a fixed natural  $k$

$$(I_r^n)_k = \{(i_1, \dots, i_p, \dots, i_r) : 1 \leq i_1 < \dots < i_p = k < \dots \leq i_r \leq n, \text{ where } 1 \leq k \leq n\}$$

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*Key words and phrases.* Subsetwise, map, linear, form.

for the indices  $j_1, \dots, j_k \in I_k^n$

$$(I_r^n)_{j_1, \dots, j_k} = \{(i_1, \dots, i_{p_1}, \dots, i_{p_k}, \dots, i_r) : \\ 1 \leq i_1 < \dots < i_{p_1} = j_1 < \dots < i_{p_k} = j_k < \dots \leq i_r \leq n\}$$

Let  $\{e_\nu\}$  be a basis of an  $n$ -dimensional vector space  $E$  and let  $x^\mu = \sum_{\nu=1}^n x_\nu^\mu e_\nu$  be vectors of  $E$ ,  $n \geq 1$ .

*Definition 2.1.* Let  $L(E^r, T)$  be the space of linear mappings of  $E^r$  into the vector space  $T$ . Consider a mapping

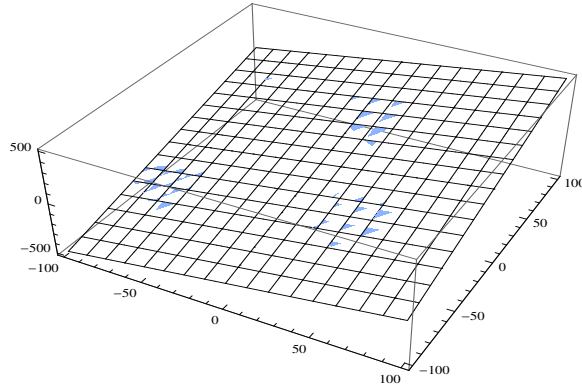
$$\begin{cases} \Phi : E^m \rightarrow T \\ \Phi : (x_1, \dots, x_m) \mapsto \sum_{\mu, \nu} \lambda_\nu^\mu \phi(x_\nu^{\mu_1} e_{\nu_1}, \dots, x_\nu^{\mu_r} e_{\nu_r}) \quad 1 \leq r \leq n, 1 \leq r \leq m, \lambda_\nu^\mu \in \Gamma \end{cases}$$

where the sum is over every system of indices  $\mu = \mu_1, \dots, \mu_r \in I_r^m$ ,  $\nu = \nu_1, \dots, \nu_r \in I_r^n$ . If  $n = m$  then  $r < n = m$ . The sum  $(x_{\nu_1}^{\mu_1} e_{\nu_1} + \dots + x_{\nu_r}^{\mu_r} e_{\nu_r})$  is denoted in short by  $x_\nu^{\mu_i} e_\nu$ , and  $\phi : E^r \rightarrow T$  is an  $r$ -linear mapping. Then  $\Phi$  is said to be  $r$ -linear with respect to the  $r$ -subsets of vectors and components, that is, an  $r$ -subsetwise linear mapping. The linear mappings  $\phi$  are the components of  $\Phi$ .

*Example 2.1.* The function  $\Phi : \mathfrak{R}^{1 \times 2} \rightarrow \mathfrak{R}$  defined by

$$\Phi(x, y) = 2x + 3y$$

is an 1-subsetwise linear function.



Graph of the function  $\Phi$ . (Obtained by Mathematica).

*Example 2.2.* The map  $\Phi : (\mathfrak{R}^2)^3 \rightarrow \mathfrak{R}^{2 \times 2}$  defined by

$$\begin{aligned} \Phi[(x_{11}, x_{21}), (x_{12}, x_{22}), (x_{13}, x_{23})] = & \lambda^{12} \begin{pmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{pmatrix} + \lambda^{13} \begin{pmatrix} x_{11} & x_{13} \\ x_{21} & x_{23} \end{pmatrix} + \\ & + \lambda^{23} \begin{pmatrix} x_{12} & x_{13} \\ x_{22} & x_{23} \end{pmatrix} \quad \lambda^\mu \in \mathfrak{R} \end{aligned}$$

is an 2-subsetwise linear map.

*Example 2.3.* Let  $f_1, \dots, f_r$  be a linearly independent set of the space  $L(E^r, T)$ , a  $r$ -subsetwise linear map is defined by

$$\Phi(x_1, \dots, x_m) = \sum_{\mu, \nu} \lambda_\nu^\mu (f_1(x_\nu^{\mu_1} e_\nu) \cdot f_2(x_\nu^{\mu_2} e_\nu) \cdots f_r(x_\nu^{\mu_r} e_\nu)) \quad \lambda_\nu^\mu \in \Gamma$$

*Theorem 2.1.* An  $r$ -subsetwise linear mapping  $\Phi$ , with  $r < m$ , is not linear

*Proof.* For any  $r$ -subsetwise linear mapping  $\Phi$ ,  $r < m$ ,

$$\begin{aligned} \Phi(x_1, \dots, x_i + y_i, \dots, x_m) &= \sum_{\mu, \nu} \lambda_\nu^\mu \phi(x_\nu^{\mu_1} e_\nu, \dots, x_\nu^i e_\nu, \dots, x_\nu^{\mu_r} e_\nu) \\ &\quad + \sum_{\mu, \nu} \lambda_\nu^\mu \phi(x_\nu^{\mu_1} e_\nu, \dots, y_\nu^i e_\nu, \dots, x_\nu^{\mu_r} e_\nu) \\ &\neq \Phi(x_1, \dots, x_i, \dots, x_m) + \Phi(x_1, \dots, y_i, \dots, x_m) \end{aligned}$$

in the first sum on the right side  $\mu = \mu_1, \dots, i, \dots, \mu_r \in I_r^m$ . Unlike, in the second sum  $\mu = \mu_1, \dots, i, \dots, \mu_r \in (I_r^m)_i$ , so this sum cannot be  $\Phi(x_1, \dots, y_i, \dots, x_m)$ .  $\square$

As a special case, if  $r = m$  then  $\Phi$  is linear.

If  $t : T \rightarrow H$  is linear and  $\Phi$  is  $r$ -swlin (subsetwise linear) map, then

$$t \circ \Phi = t \left( \sum \lambda_\nu^\mu \phi \right) = \sum \lambda_\nu^\mu t \circ \phi$$

and  $t \circ \Phi$  is a  $r$ -swlin map.

By the set  $SW(E^m, T)$  of the  $r$ -swlin maps, the following exponential functor  $F$ , from linear spaces to sets, is defined by

$$\begin{aligned} F(T) &= SW(E^m, T) && \text{for any linear space } T \\ \left\{ \begin{array}{l} F(t) : F(T) \rightarrow F(H) \\ F(t) : \Phi \mapsto t \circ \Phi \end{array} \right. && \text{for any linear } t : T \rightarrow H \end{aligned}$$

*Theorem 2.2.* For any  $r$ -swlin mapping  $\Psi : E^m \rightarrow H$  there exists a unique linear mapping  $f : E \otimes \cdots \otimes E \rightarrow H$  such that

$$f(x_1 \otimes \cdots \otimes x_m) = \Psi(x_1, \dots, x_m)$$

That is, the mapping  $\otimes : E^m \rightarrow T$  is an universal element for the functor  $F$ .

*Proof.* The proof generalizes to swlin maps the classical proof of universality of the tensor product, see [4], [6].

Uniqueness. Suppose that  $\otimes : E^m \rightarrow T$  and  $\tilde{\otimes} : E^m \rightarrow \tilde{T}$  are universal elements for the functor  $F$ , then, there exist linear maps

$$f : T \rightarrow \tilde{T} \quad \text{and} \quad g : \tilde{T} \rightarrow T$$

such that

$$f(x_1 \otimes \cdots \otimes x_m) = x_1 \tilde{\otimes} \cdots \tilde{\otimes} x_m \quad \text{and} \quad g(x_1 \tilde{\otimes} \cdots \tilde{\otimes} x_m) = x_1 \otimes \cdots \otimes x_m$$

that is

$$g \circ f(x_1 \otimes \cdots \otimes x_m) = x_1 \otimes \cdots \otimes x_m \quad \text{and} \quad f \circ g(x_1 \tilde{\otimes} \cdots \tilde{\otimes} x_m) = x_1 \tilde{\otimes} \cdots \tilde{\otimes} x_m$$

by the universality of  $\otimes$  and  $\tilde{\otimes}$  it follows, respectively

$$1_T = g \circ f \quad \text{and} \quad 1_{\tilde{T}} = f \circ g$$

thus  $f$  and  $g$  are inverse linear isomorphisms.

Existence. Consider the free vector space  $C(E^r)$  generated by the space  $E^r$ . Denote by  $N(E^r)$  the subspace of  $C(E^r)$  spanned by the vectors

$$(x_v^{\mu_1} e_v, \dots, \delta_1 y_1 + \delta_2 y_2, \dots, x_v^{\mu_r} e_v) - \delta_1 (x_v^{\mu_1} e_v, \dots, y_1, \dots, x_v^{\mu_r} e_v) \\ - \delta_2 (x_v^{\mu_1} e_v, \dots, y_2, \dots, x_v^{\mu_r} e_v)$$

for  $\mu = \mu_1, \dots, \mu_r \in I_r^m$ ,  $v = v_1, \dots, v_r \in I_r^n$ ,  $\delta_i \in \Gamma$  and  $x_v^{\mu_r} e_v, y_1, y_2 \in E^r$ . Set  $S = C(E^r)/N(E^r)$  and let  $\pi : C(E^r) \rightarrow S$  be the canonical projection. Define the map

$$\begin{cases} \otimes : E^m \rightarrow S \\ \otimes : (x_1, \dots, x_m) \mapsto \sum_{\mu, v} \lambda_v^\mu \pi(x_v^{\mu_1} e_v, \dots, x_v^{\mu_r} e_v) \end{cases}$$

Since  $\pi$  is a homomorphism, it follows that  $\otimes$  is an r-swlin map.

If  $z \in S$ , then it is a finite sum

$$z = \sum_{\tau} \delta^\tau \left( \sum_{\mu, v} \lambda_v^\mu \pi(x_v^{\mu_1} e_v, \dots, x_v^{\mu_r} e_v) \right)_\tau \\ = \sum_{\tau} \delta^\tau (x_1 \otimes \dots \otimes x_m)_\tau$$

so  $\forall z \in S$ ,  $z$  is spanned by the products  $x_1 \otimes \dots \otimes x_m$  and  $I_m \otimes = S$ .

Moreover let  $\psi : \mathfrak{E}^r \rightarrow H$  be a r-linear map. Since  $C(E^r)$  is a free vector space, there exists a unique linear map  $g$  such that the following diagram commutes

$$\begin{array}{ccc} E^r & \xrightarrow{j} & C(E^r) \\ & \searrow \psi & \downarrow g \\ & & H \end{array}$$

where  $j$  is the insertion of  $E^r$  in  $C(E^r)$ . So

$$g(x_v^{\mu_1} e_v, \dots, x_v^{\mu_r} e_v) = \psi(x_v^{\mu_1} e_v, \dots, x_v^{\mu_r} e_v)$$

If

$$z = (x_v^{\mu_1} e_v, \dots, \delta_1 y_1 + \delta_2 y_2, \dots, x_v^{\mu_r} e_v) - \delta_1 (x_v^{\mu_1} e_v, \dots, y_1, \dots, x_v^{\mu_r} e_v) \\ - \delta_2 (x_v^{\mu_1} e_v, \dots, y_2, \dots, x_v^{\mu_r} e_v)$$

is a generator of  $N(E^r)$ , then

$$g(z) = \psi(z) = \psi(x_v^{\mu_1} e_v, \dots, \delta_1 y_1 + \delta_2 y_2, \dots, x_v^{\mu_r} e_v) - \delta_1 \psi(x_v^{\mu_1} e_v, \dots, y_1, \dots, x_v^{\mu_r} e_v) \\ - \delta_2 \psi(x_v^{\mu_1} e_v, \dots, y_2, \dots, x_v^{\mu_r} e_v) \\ = 0$$

then  $N(E^r) \subseteq \text{Ker } g$ . For the principal theorem on factor spaces, see [5], there exists a unique linear map  $f$  such that the following diagram commutes

$$\begin{array}{ccc}
C(E^r) & \xrightarrow{\pi} & S \\
& \searrow g & \downarrow f \\
& & H
\end{array}$$

that is,  $\pi$  is an universal element. So

$$\begin{aligned}
(f \circ \otimes)(x_1, \dots, x_m) &= f\left(\sum_{\mu, v} \lambda_v^\mu \pi(x_v^{\mu_1} e_v, \dots, x_v^{\mu_r} e_v)\right) \\
&= \sum_{\mu, v} \lambda_v^\mu f \circ \pi(x_v^{\mu_1} e_v, \dots, x_v^{\mu_r} e_v) \\
&= \sum_{\mu, v} \lambda_v^\mu g(x_v^{\mu_1} e_v, \dots, x_v^{\mu_r} e_v) \\
&= \sum_{\mu, v} \lambda_v^\mu \psi(x_v^{\mu_1} e_v, \dots, x_v^{\mu_r} e_v) \\
&= \Psi(x_1, \dots, x_m)
\end{aligned}$$

□

*Example 2.4.* Consider the 2-swlin function  $\Phi$  defined by

$$\begin{cases} \Phi : (\mathfrak{R}^2)^3 \rightarrow \mathfrak{R} \\ \Phi : (x_1, x_2, x_3) \mapsto \lambda^{12}(x_1, x_2) + \lambda^{13}(x_1, x_3) + \lambda^{23}(x_2, x_3) \end{cases} \quad \lambda^{12}, \lambda^{13}, \lambda^{23} \in \mathfrak{R}$$

where the bilinear function  $(-, -)$ , on the right side, is the inner product in  $\mathfrak{R}^2$ . By the theorem 2.2, the map  $\otimes : (\mathfrak{R}^2)^3 \rightarrow \mathfrak{R}^2 \otimes \mathfrak{R}^2 \otimes \mathfrak{R}^2$  is universal, so an unique linear function  $f : \mathfrak{R}^2 \otimes \mathfrak{R}^2 \otimes \mathfrak{R}^2 \rightarrow \mathfrak{R}$  exists such that  $f(x_1 \otimes x_2 \otimes x_3) = \Phi(x_1, x_2, x_3)$ . Since  $\mathfrak{R}^2 \otimes \mathfrak{R}^2 \otimes \mathfrak{R}^2$  is free, the function  $f$  is determined by its values  $f(x_1 \otimes x_2 \otimes x_3)$  on the free generators  $x_1 \otimes x_2 \otimes x_3$ .

*Corollary 2.1.* For any r-swlin map  $\Phi : E^m \rightarrow T$

$$\otimes(x_1, \dots, x_m) = \sum_{\mu, v} \lambda_v^\mu (x_v^{\mu_1} e_v \otimes \dots \otimes x_v^{\mu_r} e_v)$$

*Proof.* Since  $\pi(x_v^{\mu_1} e_v, \dots, x_v^{\mu_r} e_v) = x_v^{\mu_1} e_v \otimes \dots \otimes x_v^{\mu_r} e_v$ , by the theorem 2.2

$$\Phi(x_1, \dots, x_m) = (f \circ \otimes)((x_1, \dots, x_m)) = f\left(\sum_{\mu, v} \lambda_v^\mu (x_v^{\mu_1} e_v \otimes \dots \otimes x_v^{\mu_r} e_v)\right)$$

□

*Example 2.5.* Let  $\Phi : (\Gamma^n)^n \rightarrow T$  be a 2-swlin map. The tensor product  $\otimes : \Gamma^n \times \Gamma^n \rightarrow M^{n \times n}$  is defined by  $x_{i_1} \otimes x_{i_2} = x_{i_1} x'_{i_2}$ ,  $x_i \in \Gamma^n$ , see [4], then  $\otimes :$

$(\Gamma^n)^n \rightarrow \Gamma^n \otimes \cdots \otimes \Gamma^n$  is given by

$$\begin{aligned} x_1 \otimes \cdots \otimes x_n &= \sum_{(i_1, i_2) \in I_2^n} \lambda^{(i_1, i_2)} x_{i_1} \otimes x_{i_2} \\ &= \begin{pmatrix} \sum_{(i_1, i_2) \in I_2^n} \lambda^{(i_1, i_2)} x_{1i_1} x_{1i_2} & \cdots & \sum_{(i_1, i_2) \in I_2^n} \lambda^{(i_1, i_2)} x_{1i_1} x_{ni_2} \\ \cdots & \cdots & \cdots \\ \sum_{(i_1, i_2) \in I_2^n} \lambda^{(i_1, i_2)} x_{ni_1} x_{1i_2} & \cdots & \sum_{(i_1, i_2) \in I_2^n} \lambda^{(i_1, i_2)} x_{ni_1} x_{ni_2} \end{pmatrix} \end{aligned}$$

### 3. $\{r, \lambda\}$ - DETERMINANT

If  $\sigma$  is a permutation,  $\sigma \in S_r$ , then the mapping  $\sigma\phi : \mathcal{E}^r \rightarrow F$  is defined by  $\sigma\phi(x_1, \dots, x_r) = \phi(x_{\sigma_1}, \dots, x_{\sigma_r})$ . More generally

*Definition 3.1.* Let  $\Phi(x_1, \dots, x_m)$  be an  $r$ -swlin map, for any permutation  $\sigma \in S_r$ , the mapping  $\sigma\Phi : E^m \rightarrow T$ , is defined by

$$\sigma\Phi(x_1, \dots, x_m) = \sum_{\mu, \nu} \lambda_\nu^\mu \sigma\phi(x_\nu^{\mu_1} e_\nu, \dots, x_\nu^{\mu_r} e_\nu) = \sum_{\mu, \nu} \lambda_\nu^\mu \phi(x_\nu^{\sigma(\mu_1)} e_\nu, \dots, x_\nu^{\sigma(\mu_r)} e_\nu)$$

*Definition 3.2.* An  $r$ -swlin map  $\Phi(x_1, \dots, x_m)$  is said skewsymmetric if for any  $\sigma \in S_r$  is  $\sigma\Phi = \epsilon_\sigma \Phi$  where  $\epsilon_\sigma = 1$  ( $\epsilon_\sigma = -1$ ) for any even (odd) permutation  $\sigma$ .

*Theorem 3.1.* An  $r$ -swlin map  $\Phi = \sum \lambda_\nu^\mu \phi$  is skewsymmetric if and only if  $\phi$  is skewsymmetric.

*Proof.* Suppose  $\phi$  skewsymmetric, then

$$\sigma\Phi = \sum_{\mu, \nu} \lambda_\nu^\mu \sigma\phi(x_\nu^{\mu_1} e_\nu, \dots, x_\nu^{\mu_r} e_\nu) = \sum_{\mu, \nu} \lambda_\nu^\mu \epsilon_\sigma \phi(x_\nu^{\mu_1} e_\nu, \dots, x_\nu^{\mu_r} e_\nu) = \epsilon_\sigma \Phi$$

Conversely,  $\sigma\Phi = \epsilon_\sigma \Phi$  implies

$$\sum_{\mu, \nu} \lambda_\nu^\mu \sigma\phi = \sum_{\mu, \nu} \lambda_\nu^\mu \epsilon_\sigma \phi$$

so  $\sum_{\mu, \nu} \lambda_\nu^\mu (\sigma\phi - \epsilon_\sigma \phi) = 0$  for all  $x_\nu^{\mu_1} e_\nu, \dots, x_\nu^{\mu_r} e_\nu$ , then  $\sigma\phi = \epsilon_\sigma \phi$ .  $\square$

*Theorem 3.2.* Every  $r$ -swlin map  $\Phi(x_1, \dots, x_m)$  determines an  $r$ -swlin skewsymmetric map  $\Psi$ , given by

$$\Psi = \sum_{\sigma} \epsilon_\sigma \sigma\Phi = \sum_{\mu, \nu} \sum_{\sigma} \lambda_\nu^\mu \epsilon_\sigma \sigma\phi(x_\nu^{\mu_1} e_\nu, \dots, x_\nu^{\mu_r} e_\nu)$$

where the second sum on right side is over all permutations  $\sigma \in S_r$ .

*Proof.* For any  $\tau \in S_r$

$$\tau\Psi = \sum_{\mu, \nu} \tau \left( \sum_{\sigma} \lambda_\nu^\mu \epsilon_\sigma \sigma\phi \right) = \sum_{\mu, \nu} \epsilon_\tau \left( \sum_{\sigma} \lambda_\nu^\mu \epsilon_\sigma \sigma\phi \right) = \epsilon_\tau \left( \sum_{\mu, \nu} \sum_{\sigma} \lambda_\nu^\mu \epsilon_\sigma \sigma\phi \right) = \epsilon_\tau \Psi.$$

$\square$

*Theorem 3.3.* Let  $\Phi = \sum_{\mu, \nu} \lambda_\nu^\mu \phi : E^m \rightarrow F$  be an  $r$ -swlin skewsymmetric map, then  $\Phi$  is completely determined by its values on a basis of  $E$  and by the constants  $\lambda_\nu^\mu$ .

*Proof.* Let  $\{e_\nu\}$  be a basis of  $E$ . Let  $x^i = \sum_{\xi=1}^n x_\xi^i e_\xi$ ,  $i = 1, \dots, m$  be vectors in  $E$  and  $X = (x_\xi^i)$ , then

$$\begin{aligned} \Phi(x_1, \dots, x_m) &= \Phi(\sum_{\xi=1}^n x_\xi^1 e_\xi, \dots, \sum_{\xi=1}^n x_\xi^m e_\xi) \\ &= \sum_{\mu, \nu} \lambda_\nu^\mu \phi((\sum_{\xi=1}^n x_\xi^{\mu_1} e_\xi)_\nu, \dots, (\sum_{\xi=1}^n x_\xi^{\mu_r} e_\xi)_\nu) \quad \nu \in I_r^n, \mu \in I_r^m \\ &= \sum_{\mu, \nu} \lambda_\nu^\mu (\sum_{\rho=1, \dots, \rho_r} \epsilon_\rho x_{\nu_{\rho_1}}^{\mu_1} \cdots x_{\nu_{\rho_r}}^{\mu_r} \phi(e_{\nu_{\rho_1}}, \dots, e_{\nu_{\rho_r}})) \quad \rho \in S_r \\ &= \sum_{\mu, \nu} \lambda_\nu^\mu |X_\nu^\mu| \phi(e_{\nu_1}, \dots, e_{\nu_r}) \end{aligned}$$

where  $X_\nu^\mu$  is the square submatrix of  $X$  determined by rows indexed by  $\nu$  and columns indexed by  $\mu$ .  $\square$

*Example 3.1.* Let  $\Phi : (\mathfrak{R}^3)^3 \rightarrow \mathfrak{R}^3$  be a 2-swlin skewsymmetric map defined by

$$\Phi(x_1, x_2, x_3) = \sum_{(i_1, i_2), (j_1, j_2) \in I_2^3} \lambda_{i_1, i_2}^{j_1, j_2} \phi \begin{pmatrix} x_{i_1, j_1} & x_{i_1, j_2} \\ x_{i_2, j_1} & x_{i_2, j_2} \end{pmatrix}$$

where  $x_i = \sum_{k=1}^3 x_{k,i} e_k \in \mathfrak{R}^3$ . Then

$$\begin{aligned} \Phi(x_1, x_2, x_3) &= \sum_{(i_1, i_2), (j_1, j_2) \in I_2^3} \lambda_{i_1, i_2}^{j_1, j_2} \phi(x_{i_1, j_1} e_{i_1} + x_{i_2, j_1} e_{i_2}, x_{i_1, j_2} e_{i_1} + x_{i_2, j_2} e_{i_2}) \\ &= \sum_{(i_1, i_2), (j_1, j_2) \in I_2^3} \lambda_{i_1, i_2}^{j_1, j_2} \phi \begin{vmatrix} x_{i_1, j_1} & x_{i_1, j_2} \\ x_{i_2, j_1} & x_{i_2, j_2} \end{vmatrix} \phi(e_{i_1}, e_{i_2}) \end{aligned}$$

*Definition 3.3.* Let  $\{e_\nu\}$  be a basis of  $E$ , then an  $r$ -swlin skewsymmetric map  $\Delta_E(x_1, \dots, x_m) : E^m \rightarrow \Gamma$  such that  $\phi(e_{\nu_1}, \dots, e_{\nu_r}) = 1$ ,  $\nu \in I_r^n$ , is said an  $r$ -determinant function.

The scalar  $det_{r, \lambda} X = \sum_{\mu, \nu} \lambda_\nu^\mu |X_\nu^\mu|$  will be said the  $(r, \lambda)$ -determinant of  $X = (x_\xi^i)$ , relative to the basis  $\{e_\nu\}$ . If  $\lambda_\nu^\mu = |X_\nu^\mu|$  we denote  $det_r X = |X|_r = \sum_{\mu, \nu} |X_\nu^\mu|^2$ , see [2].

*Example 3.2.* In order to obtain a non-trivial example of  $r$ -determinant function, consider a 2-swlin function  $\Phi = \sum_{\mu, \nu} \lambda_\nu^\mu \phi$  defined by

$$\Phi(x_1, \dots, x_m) = \sum_{\mu, \nu} \lambda_\nu^\mu \langle e^{*\mu_1}, x_{\nu_1}^{\mu_1} e_\nu \rangle \cdots \langle e^{*\mu_r}, x_{\nu_r}^{\mu_r} e_\nu \rangle$$

that is

$$\phi(x_{\nu_1}^{\mu_1} e_\nu, \dots, x_{\nu_r}^{\mu_r} e_\nu) = \langle e^{*\mu_1}, x_{\nu_1}^{\mu_1} e_\nu \rangle \cdots \langle e^{*\mu_r}, x_{\nu_r}^{\mu_r} e_\nu \rangle$$

where  $\{e_\nu\}$ ,  $\{e^{*\nu}\}$  are a pair of dual bases in  $E$  and  $E^* = L(E) = \{f : f : E \rightarrow \Gamma, f \text{ linear}\}$  respectively, with  $\dim E = \dim E^* \geq r$ . The bilinear function  $\langle, \rangle$  is non-degenerate and it is defined by

$$\langle e^{*\mu_i}, x_{\nu_i}^{\mu_i} e_\nu \rangle = e^{*\mu_i}(x_{\nu_i}^{\mu_i} e_\nu)$$

then

$$\begin{aligned} \Phi(x_1, \dots, x_m) &= \sum_{\mu} \lambda_\mu^\mu \langle e^{*\mu_1}, x_{\mu_1}^{\mu_1} e_{\mu_1} \rangle \cdots \langle e^{*\mu_r}, x_{\mu_r}^{\mu_r} e_{\mu_r} \rangle \\ &= \sum_{\mu} \lambda_\mu^\mu x_{\mu_1}^{\mu_1} \cdots x_{\mu_r}^{\mu_r} \end{aligned}$$

The set of the r-swlin maps is denoted by  $SW(E^m, T)$ . The exponential functor  $F$ , from linear spaces to sets, is defined by

$$F(T) = SW(E^m, T) \quad \text{for any linear space } T$$

$$\begin{cases} F(t) : F(T) \rightarrow F(H) \\ F(t) : \Phi \mapsto t \circ \Phi \end{cases} \quad \text{for any linear } t : T \rightarrow H$$

The following proposition states the universality of the r-determinant function.

*Theorem 3.4.* Let  $\Delta_E = \sum_{\mu, \nu} \lambda_\nu^\mu \phi : E^m \rightarrow \Gamma$  be an r-determinant function in  $E$ , then for any r-swlin skewsymmetric mapping  $\Theta = \sum_{\mu, \nu} \lambda_\nu^\mu \theta : E^m \rightarrow F$ , there is an unique vector  $f \in F$  such that

$$\Theta(x_1, \dots, x_m) = (\Delta_E(x_1, \dots, x_m))(f) = \sum_{\mu, \nu} \lambda_\nu^\mu |X_\nu^\mu| f_\nu \quad \mu \in I_r^m, \nu \in I_r^n, x_i \in E$$

where  $f_\nu$  are the components of the vector

$$f = (\theta(e_{v_1^1}, \dots, e_{v_r^1}), \dots, \theta(e_{v_1^{\binom{n}{r}}}, \dots, e_{v_r^{\binom{n}{r}}}))$$

and  $v^i$  are the  $\binom{n}{r}$  elements of  $I_r^n$ .

*Proof.* Let  $\{e_i\}$ ,  $i = 1, \dots, n$  be a basis of  $E$  such that

$$\Delta_E(x_1, \dots, x_m) = \sum_{\mu, \nu} \lambda_\nu^\mu |X_\nu^\mu| \phi(e_{v_1}, \dots, e_{v_r}) = \sum_{\mu, \nu} \lambda_\nu^\mu |X_\nu^\mu|$$

that is,  $\phi(e_{v_1}, \dots, e_{v_r}) = 1$ .

Then, for any r-swlin skewsymmetric map

$$\Psi(x_1, \dots, x_m) = \sum_{\mu, \nu} \lambda_\nu^\mu |X_\nu^\mu| \psi = (\Delta_E(x_1, \dots, x_m))(f)$$

it follows

$$\begin{aligned} \psi(e_{v_1}, \dots, e_{v_r}) &= \phi(e_{v_1}, \dots, e_{v_r}) \theta(e_{v_1}, \dots, e_{v_r}) \\ &= 1 \cdot \theta(e_{v_1}, \dots, e_{v_r}) \end{aligned}$$

so  $\Theta$  and  $\Psi$  have the same values on the basis  $\{e_\nu\}$  and by theorem 3.3 it follows  $\Theta = \Psi$ .  $\square$

If  $\Delta_E$  and  $\Delta'_E$  are two r-determinant functions in  $E$ , then  $\eta \Delta_E + \theta \Delta'_E$ ,  $\eta, \theta \in \Gamma$ , is a r-determinant function too.

Let  $\Delta_F$  be an r-determinant function in  $F$  and let  $\psi : E \rightarrow F$  be a linear mapping of vector spaces, where  $\dim E = n$ ,  $\dim F = t$ , then  $\Delta_\psi : E^m \rightarrow \Gamma$ , defined by

$$\Delta_\psi(x_1, \dots, x_m) = \Delta_F(\psi x_1, \dots, \psi x_m) = \sum_{\mu, \tau} \lambda_\tau^\mu \phi_F((\psi x^{\mu_1})_\tau, \dots, (\psi x^{\mu_r})_\tau)$$

is an r-determinant function in  $E$ , where  $\phi_F : F^r \rightarrow \Gamma$  is an r-linear mapping on  $F$ ,  $\mu \in I_r^m$ ,  $\tau \in I_r^t$ .

By theorem 3.4,  $\Delta_\psi = \Delta_F(f) = \sum_{\mu, \nu, \tau} \lambda_\tau^\mu |X_\nu^\tau| f_\nu$  for an unique vector  $f = (f_\nu)$ .

Let  $\Delta'_F$  be another nonnull swlin skewsymmetric map, then

$$\Delta'_F = \Delta_F(g) = \sum_{\mu, \nu, \tau} \lambda_\tau^\mu |X_\nu^\tau| g_\nu$$



and

$$\Delta'_\psi = \Delta_\psi(g) = (\Delta_F(f))(g) = \sum_{\mu, \nu, \tau} \lambda_\tau^\mu |X_\nu^\tau| f_\nu g_\nu = \Delta'_F(f_\nu)$$

so the vector  $f$  does not depend on the choice of  $\Delta_F$  and it is determined by the map  $\psi$ , then the notation  $f = \det \psi$ .

*Example 3.3.* Let  $\psi$  and  $A_\psi$  be a linear map and its matrix respectively, defined by

$$\begin{cases} \psi : \mathfrak{R}^2 \rightarrow \mathfrak{R}^3 \\ \psi : (x, y) \mapsto (x, y, x + y) \end{cases} \quad A_\psi = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{pmatrix}$$

besides let  $\Delta_{\mathfrak{R}^3} : (\mathfrak{R}^3)^3 \rightarrow \mathfrak{R}$  be a 2-determinant function and  $x_i \in \mathfrak{R}^2$ , then

$$\begin{aligned} \Delta_\psi &= \Delta_{\mathfrak{R}^3}(\psi x_1, \psi x_2, \psi x_3) = \lambda^{12} \phi(\psi x_1, \psi x_2) + \lambda^{13} \phi(\psi x_1, \psi x_3) + \lambda^{23} \phi(\psi x_2, \psi x_3) \\ &= \lambda^{12} \phi\left(\sum_{i=1}^2 x_{i1} \psi e_i, \sum_{i=1}^2 x_{i2} \psi e_i\right) + \lambda^{13} \phi\left(\sum_{i=1}^2 x_{i1} \psi e_i, \sum_{i=1}^2 x_{i3} \psi e_i\right) \\ &\quad + \lambda^{23} \phi\left(\sum_{i=1}^2 x_{i2} \psi e_i, \sum_{i=1}^2 x_{i3} \psi e_i\right) \\ &= \lambda^{12} |X^{12}| \phi(\psi e_1, \psi e_2) + \lambda^{13} |X^{13}| \phi(\psi e_1, \psi e_2) + \lambda^{23} |X^{23}| \phi(\psi e_1, \psi e_2) \end{aligned}$$

where  $|X^{ij}| = \begin{vmatrix} x_{1i} & x_{1j} \\ x_{2i} & x_{2j} \end{vmatrix}$ . Since

$$\begin{aligned} \phi(\psi e_1, \psi e_2) &= \phi((1, 0, 1), (0, 1, 1)) = \lambda_{12} \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} + \lambda_{13} \begin{vmatrix} 1 & 0 \\ 1 & 1 \end{vmatrix} + \lambda_{23} \begin{vmatrix} 0 & 1 \\ 1 & 1 \end{vmatrix} \\ &= \lambda_{12} + \lambda_{13} - \lambda_{23} \end{aligned}$$

then

$$\begin{aligned} \Delta_\psi &= \lambda^{12} |X^{12}| \det_{2,\lambda} \psi + \lambda^{13} |X^{13}| \det_{2,\lambda} \psi + \lambda^{23} |X^{23}| \det_{2,\lambda} \psi \\ &= \Delta_{\mathfrak{R}^3}(\det_{2,\lambda} \psi) \end{aligned}$$

The expression for  $\det \psi$  may be obtained immediately by the matrix  $A_\psi$ , see [2]

$$\det_{2,\lambda} A_\psi = \det_{2,\lambda} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{pmatrix} = \lambda_{12} \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} + \lambda_{13} \begin{vmatrix} 1 & 0 \\ 1 & 1 \end{vmatrix} + \lambda_{23} \begin{vmatrix} 0 & 1 \\ 1 & 1 \end{vmatrix} = \lambda_{12} + \lambda_{13} - \lambda_{23}$$

*Theorem 3.5.* Let  $\psi : E \rightarrow F$  be a linear mapping and  $A_\psi = (\alpha_\nu^\tau)$  its matrix relative to the bases  $\{e_\nu\}$ ,  $\{f_\tau\}$ ,  $\nu = 1, \dots, n$ ,  $\tau = 1, \dots, t$ . Let  $\Delta_F = \sum_{\mu, \tau} \lambda_\tau^\mu \phi_F : F^m \rightarrow \Gamma$  be an r-determinant function. If  $\phi_F(f_\tau^{\mu_1}, \dots, f_\tau^{\mu_r}) = 1$ , then

i)

$$\Delta_\psi(x_1, \dots, x_m) = \sum_{\mu, \tau} \lambda_\tau^\mu \left( \sum_\nu |X_\nu^\mu| |A_\nu^\tau| \right) \quad \mu \in I_r^m, \nu \in I_r^n, \tau \in I_r^t$$

ii)

$$\Delta_\psi(e_1, \dots, e_n) = \sum_{\nu, \tau} \lambda_\tau^\nu |A_\nu^\tau|$$

where  $A_v^\tau$  is the submatrix of  $A$  determined by rows indexed by  $v$  and columns indexed by  $\tau$ , for  $v = v_1, \dots, v_r \in I_r^n$ ,  $\tau = \tau_1, \dots, \tau_r \in I_r^t$ . The vectors  $x_1, \dots, x_m$ , relative to the basis  $\{e_v\}$ , are expressed by  $x^\mu = \sum_{v=1}^n x_v^\mu e_v$ ,  $\mu = 1, \dots, m$  and  $X = (x_v^\mu)$ .

*Proof.* i)

$$\begin{aligned} \Delta_\psi(x_1, \dots, x_m) &= \Delta_F(\psi x_1, \dots, \psi x_m) = \Delta_F(\sum_{v=1}^n x_v^1 \psi e_v, \dots, \sum_{v=1}^n x_v^m \psi e_v) \\ &= \Delta_F(\sum_{v=1}^n x_v^1 \sum_{\tau=1}^t \alpha_1^\tau f_\tau, \dots, \sum_{v=1}^n x_v^m \sum_{\tau=1}^t \alpha_m^\tau f_\tau) \\ &= \Delta_F(\sum_{\tau=1}^t (\sum_{v=1}^n x_v^1 \alpha_v^\tau) f_\tau, \dots, \sum_{\tau=1}^t (\sum_{v=1}^n x_v^m \alpha_v^\tau) f_\tau) \\ &= \sum_{\mu, \tau} \lambda_\tau^\mu \phi_F((\sum_{v=1}^n x_v^{\mu_1} \alpha_v^{\tau_{\rho_1}}) f_\tau, \dots, (\sum_{v=1}^n x_v^{\mu_r} \alpha_v^{\tau_{\rho_r}}) f_\tau) \quad \tau \in I_r^t, \mu \in I_r^m \\ &= \sum_{\mu, \tau} \lambda_\tau^\mu (\sum_{\rho=\rho_1, \dots, \rho_r} \epsilon_\rho (\sum_{v=1}^n x_v^{\mu_1} \alpha_v^{\tau_{\rho_1}}) \cdots (\sum_{v=1}^n x_v^{\mu_r} \alpha_v^{\tau_{\rho_r}})) \phi_F(f_\tau^{\rho_1}, \dots, f_\tau^{\rho_r}) \end{aligned}$$

$\rho \in S_r$ , by

$$\sum_{\rho=\rho_1, \dots, \rho_r} \epsilon_\rho (\sum_{v=1}^n x_v^{\mu_1} \alpha_v^{\tau_{\rho_1}}) \cdots (\sum_{v=1}^n x_v^{\mu_r} \alpha_v^{\tau_{\rho_r}}) = \sum_v |X_v^\mu| |A_v^\tau|$$

it follows i).

ii) It is a special case of i) for  $X = I_n$ .  $\square$

The scalar  $\det_{r, \lambda} \psi = \sum_{\mu, v} \lambda_v^\mu |A_v^\mu|$  will be called the  $(r, \lambda)$ -determinant of  $\psi$ , relative to the bases  $\{e_v\}, \{f_\mu\}$ . If  $\lambda_v^\mu = |A_v^\mu|$ , then  $\sum_{\mu, v} |A_v^\mu|^2$  will be denoted by  $\det_r \psi$  or  $|\psi|_r$ .

*Theorem 3.6.* Let  $\psi : E \rightarrow F$  and  $\theta : F \rightarrow G$  be linear mappings of vector spaces. Let  $\Delta_F$  be a determinant function in  $F$ . If  $x_1, \dots, x_m$  are vectors in  $E$ , then

$$\Delta_{\theta \circ \psi}(x_1, \dots, x_m) = \Delta_\theta \circ \Delta_\psi(x_1, \dots, x_m)$$

*Proof.*

$$\begin{aligned} \Delta_{\theta \circ \psi}(x_1, \dots, x_m) &= \Delta_G(\theta \circ \psi(x_1, \dots, x_m)) \\ &= \Delta_\theta(\psi(x_1, \dots, \psi x_m)) \\ &= \Delta_\theta \circ \Delta_\psi(x_1, \dots, x_m) \end{aligned}$$

$\square$

#### 4. THE (T,K)-FORMS

Let  $\mathfrak{R}_p^n$  be the tangent space of  $\mathfrak{R}^n$  at the point  $p$  and let  $(\mathfrak{R}_p^n)^*$  be the dual space. Let  $\Lambda^k(\mathfrak{R}_p^n)^*$  be the linear space of the  $k$ -linear alternating maps  $\phi : (\mathfrak{R}_p^n)^k \rightarrow \mathfrak{R}$ , then denote by  $\Lambda_t^k(\mathfrak{R}_p^n)^*$ , with  $k \leq t \leq n$ , the set of all  $k$ -linear alternating maps  $\phi : (\mathfrak{R}_p^n)^t \rightarrow \mathfrak{R}$ . The set  $\Lambda_t^k(\mathfrak{R}_p^n)^*$ , by the usual operations of functions, is a linear space.

If  $\phi_1, \dots, \phi_t$  belong to  $(\mathfrak{R}_p^n)^*$ , then an element  $\phi_1 \wedge \dots \wedge \phi_t \in \Lambda_t^k(\mathfrak{R}_p^n)^*$  is obtained by setting

$$(\phi_1 \wedge \dots \wedge \phi_t)(v_1, \dots, v_k) = \det_{k, \lambda} \phi_i(v_j) = \begin{vmatrix} \phi_1(v_1) & \cdots & \phi_1(v_k) \\ \cdots & \cdots & \cdots \\ \phi_t(v_1) & \cdots & \phi_t(v_k) \end{vmatrix}$$

where  $i = 1, \dots, t$ ,  $j = 1, \dots, k$  and  $v_j \in \mathfrak{R}^n$ .

Observe that  $\phi_1 \wedge \dots \wedge \phi_t$  is  $k$ -linear and alternate.

*Example 4.1.* When  $\phi_1, \phi_2, \phi_3$  belong to  $(\mathfrak{R}_p^3)^*$ , an element  $\phi_1 \wedge \phi_2 \wedge \phi_3 \in \Lambda_3^2(\mathfrak{R}_p^3)^*$  is obtained by the 2-swlin skewsymmetric map

$$\begin{aligned} (\phi_1 \wedge \phi_2 \wedge \phi_3)(v_1, v_2) &= \det_{2,\lambda} \phi_i(v_j) = \begin{vmatrix} \phi_1(v_1) & \phi_1(v_2) \\ \phi_2(v_1) & \phi_2(v_2) \\ \phi_3(v_1) & \phi_3(v_2) \end{vmatrix} \\ &= \sum_{i_1 < i_2} \lambda_{i_1 i_2} \begin{vmatrix} \phi_{i_1}(v_1) & \phi_{i_1}(v_2) \\ \phi_{i_2}(v_1) & \phi_{i_2}(v_2) \end{vmatrix} \\ &\quad (i_1, i_2) \in I_2^3, \lambda_{i_1 i_2} \in \mathfrak{R} \end{aligned}$$

and  $\phi_1 \wedge \phi_2 \wedge \phi_3$  is a bilinear alternating map on the vectors  $v_1, v_2$ .

Let  $x^i : \mathfrak{R}^n \rightarrow \mathfrak{R}$  be the function which assigns to each point of  $\mathfrak{R}^n$  its  $i^{\text{th}}$ -coordinate. Then  $(dx^i)_p$  is a linear map in  $(\mathfrak{R}^n)^*$  and the set  $\{(dx^i)_p; i = 1, \dots, n\}$  is the dual basis of the standard  $\{(e_i)_p\}$ . The element  $(dx^{i_1})_p \wedge \dots \wedge (dx^{i_t})_p$  is denoted by  $(dx^{i_1} \wedge \dots \wedge dx^{i_t})_p$  and belongs to  $\Lambda_t^k(\mathfrak{R}_p^n)^*$ .

*Theorem 4.1.* The set  $\{(dx^{i_1} \wedge \dots \wedge dx^{i_t})_p\}$ ,  $i_1, \dots, i_t \in I_t^n$  is a basis for  $\Lambda_t^k(\mathfrak{R}_p^n)^*$ .

*Proof.* the elements of  $\{(dx^{i_1} \wedge \dots \wedge dx^{i_t})_p\}$  are linearly independent. In fact, suppose

$$\sum_{i_1, \dots, i_t \in I_t^n} a_{i_1, \dots, i_t} dx^{i_1} \wedge \dots \wedge dx^{i_t} = 0$$

then, for any  $(e_{j_1}, \dots, e_{j_k})$ , with  $j_1, \dots, j_k \in I_k^n$ , it follows

$$\begin{aligned} &\sum_{i_1, \dots, i_t \in I_t^n} a_{i_1, \dots, i_t} dx^{i_1} \wedge \dots \wedge dx^{i_t}(e_{j_1}, \dots, e_{j_k}) \\ &= \sum_{i_1, \dots, i_t \in I_t^n} a_{i_1, \dots, i_t} \begin{vmatrix} dx^{i_1} e_{j_1} & \dots & dx^{i_1} e_{j_k} \\ \dots & \dots & \dots \\ dx^{i_t} e_{j_1} & \dots & dx^{i_t} e_{j_k} \end{vmatrix} \\ &= \sum_{i_1, \dots, i_t \in I_t^n} a_{i_1, \dots, i_t} \begin{vmatrix} \delta_{j_1}^{i_1} & \dots & \delta_{j_k}^{i_1} \\ \dots & \dots & \dots \\ \delta_{j_1}^{i_t} & \dots & \delta_{j_k}^{i_t} \end{vmatrix} \\ &= \sum_{r_1, \dots, r_t} \lambda_{r_1, \dots, r_t} a_{r_1, \dots, r_t} \quad r_1, \dots, r_t \in (I_t^n)_{j_1, \dots, j_k} \\ &= 0 \end{aligned}$$

Without loss of generality, suppose  $\lambda_{r_1, \dots, r_t}$  all equal, then the  $\binom{n}{k}$  equations  $\sum_{r_1, \dots, r_t} a_{r_1, \dots, r_t} = 0$ ,  $r_1, \dots, r_t \in (I_t^n)_{j_1, \dots, j_k}$ ,  $j_1, \dots, j_k \in I_k^n$ , are a linear omogeneous full rank system, so it has only the trivial solution. That is  $a_{i_1, \dots, i_t} = 0$ .

The set  $\{(dx^{i_1} \wedge \dots \wedge dx^{i_t})_p\}$  spans  $\Lambda_t^k(\mathfrak{R}_p^n)^*$ , in other words any  $\phi \in \Lambda_t^k(\mathfrak{R}_p^n)^*$  may be written

$$\phi = \sum_{i_1, \dots, i_t \in I_t^n} a_{i_1, \dots, i_t} dx^{i_1} \wedge \dots \wedge dx^{i_t} \quad i_1, \dots, i_t \in I_t^n$$

in fact, if

$$\psi = \sum_{i_1, \dots, i_t \in I_t^n} \phi(e_{i_1}, \dots, e_{i_t}) dx^{i_1} \wedge \dots \wedge dx^{i_t}$$

then  $\psi(e_{i_1}, \dots, e_{i_t}) = \phi(e_{i_1}, \dots, e_{i_t})$  for all  $i_1, \dots, i_t \in I_t^n$ , so  $\psi = \phi$ . Setting  $\psi(e_{i_1}, \dots, e_{i_t}) = a_{i_1, \dots, i_t}$ , it follows the expression of  $\phi$ .  $\square$

The above proposition generalizes the known theorem about the basis  $\{dx^{i_1} \wedge \dots \wedge dx^{i_k}\}$  of the space  $\Lambda^k(\mathfrak{R}_p^n)^*$ , see [1].

*Theorem 4.2.* The linear spaces  $\Lambda_t^k(\mathfrak{R}_p^n)^*$  and  $\Lambda^k(\mathfrak{R}_p^n)^*$  coincide.

*Proof.* Let  $\omega = (\phi_1 \wedge \dots \wedge \phi_t)(v_1, \dots, v_k) \in \Lambda_t^k(\mathfrak{R}_p^n)^*$ , then

$$\begin{aligned} \omega &= \sum_{i_1, \dots, i_k \in I_k^n} \lambda_{i_1, \dots, i_k} \begin{vmatrix} \phi_{i_1}(v_1) & \dots & \phi_{i_1}(v_k) \\ \dots & \dots & \dots \\ \phi_{i_k}(v_1) & \dots & \phi_{i_k}(v_k) \end{vmatrix} \\ &= \sum_{i_1, \dots, i_k \in I_k^n} \lambda_{i_1, \dots, i_k} (\phi_1 \wedge \dots \wedge \phi_k)(v_1, \dots, v_k) \end{aligned}$$

so  $\omega \in \Lambda^k(\mathfrak{R}_p^n)^*$ . Conversely, let 0 be the null function in  $(\mathfrak{R}_p^n)^*$ , then any  $\psi \in \Lambda^k(\mathfrak{R}_p^n)^*$  may be written as

$$\psi = (\psi_1 \wedge \dots \wedge \psi_k)(v_1, \dots, v_k) = (\psi_1 \wedge \dots \wedge \psi_k \wedge 0 \wedge \dots \wedge 0)(v_1, \dots, v_k)$$

so  $\psi \in \Lambda_t^k(\mathfrak{R}_p^n)^*$ .  $\square$

If  $\omega \in \Lambda_t^k(\mathfrak{R}_p^n)^*$ , then  $\omega$  may be decomposed by elements of  $\Lambda_{t-j}^k(\mathfrak{R}_p^n)^*$ , where  $k \leq t-j \leq t$ , in fact

*Theorem 4.3.* Let  $\omega = (\phi_1 \wedge \dots \wedge \phi_t)(v_1, \dots, v_k) \in \Lambda_t^k(\mathfrak{R}_p^n)^*$ , then

$$\omega = \frac{\lambda_{i_1, \dots, i_{t-j}}}{(t-k) \dots (t-k-j+1)} \sum_{I_{t-j}^k} (\phi_{i_1} \wedge \dots \wedge \phi_{i_{t-j}})(v_1, \dots, v_k)$$

*Proof.*

$$\begin{aligned} \omega &= \frac{\lambda_{i_1, \dots, i_{t-1}}}{(t-k)} \sum_{I_{t-1}^k} (\phi_{i_1} \wedge \dots \wedge \phi_{i_{t-1}})(v_1, \dots, v_k) \\ &= \dots \quad \dots \quad \dots \\ &= \frac{\lambda_{i_1, \dots, i_{t-j}}}{(t-k) \dots (t-k-j+1)} \sum_{I_{t-j}^k} (\phi_{i_1} \wedge \dots \wedge \phi_{i_{t-j}})(v_1, \dots, v_k) \end{aligned}$$

indeed  $\omega$  is the sum of  $\binom{t}{k}$  determinants, the last right side has the same number

$$\frac{t \dots (t-j+2)}{(t-k) \dots (t-k-j+1)} \binom{t-j}{k} \binom{t-j+1}{t-j}$$

$\square$

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